





Current-Driven Kink Instability in Magnetically Dominated Rotating Relativistic Jets

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Mizuno, Lyubarsky, Nishikawa, & Hardee 2012, ApJ, 757, 16

The Innermost Regions of Relativistic Jets and Their Magnetic Fields, Granada, Spain, June 10-14, 2013

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Relativistic Regime

- Kinetic energy >> rest-mass energy
 - Fluid velocity ~ light speed
 - Lorentz factor g >> 1
 - Relativistic jets/ejecta/wind/blast waves (shocks) in AGNs, GRBs, Pulsars
- Thermal energy >> rest-mass energy
 - Plasma temperature >> ion rest mass energy
 - $p/rc^2 \sim k_B T/mc^2 >> 1$
 - GRBs, magnetar flare?, Pulsar wind nebulae
- Magnetic energy >> rest-mass energy
 - Magnetization parameter s >> 1
 - s=Poyniting to kinetic energy ratio = $B^2/4 prc^2 g^2$
 - Pulsars magnetosphere, Magnetars
- Gravitational energy >> rest-mass energy
 - $GMm/rmc^2 = r_g/r > 1$
 - Black hole, Neutron star
- Radiation energy >> rest-mass energy
 - $E'_{r}/rc^{2} >> 1$
 - Supercritical accretion flow

Relativistic Jets

- *Relativistic jets: outflow of highly collimated plasma*
 - Microquasars, Active Galactic Nuclei, Gamma-Ray Bursts, Jet velocity ~c
 - Generic systems: Compact object (White Dwarf, Neutron Star, Black Hole)+ Accretion Disk
- Key Issues of Relativistic Jets
 - Acceleration & Collimation
 - Propagation & Stability
- Modeling for Jet Production
 - Magnetohydrodynamics (MHD)
 - Relativity (SR or GR)
- Modeling of Jet Emission
 - Particle Acceleration
 - Radiation mechanism

Radio observation of M87 jet



Relativistic Jets in Universe



Mirabel & Rodoriguez 1998

Relativistic Jets Formation from GRMHD Simulations

- Many GRMHD simulations of jet formation (e.g., Hawley & Krolik 2006, McKinney 2006, Hardee et al. 2007) suggest that
 - a jet spine (Poynting-flux jet) driven by the magnetic fields threading the ergosphere via MHD process or Blandford-Znajek process
 - may be surrounded by a broad sheath wind driven by the magnetic fields anchored in the accretion disk.
 - High magnetized flow accelerates G>>1, but most of energy remains in B field. Non-rotating BH Fast-rotating BH





M87: Jet Launching & Collimation Region



The Five Regions of AGN Jet Propagation

- Hot Spot/Lobe: ~ $10^9 r_s$ (~100 kpc; or 20')
 - X Outer jet is <u>not</u> Poynting-Flux Dominated
- Kinetic-Flux-Dominated (KFD) Jet: $\sim 10^3 10^9 r_S$ (0.1 - 10⁵ pc; 1 mas - 20')
- Transition Region: ~10^{2.5} № (< 0.1 pc; < 1 mas)
 Poynting-Flux Dominated (PFD) 𝔅 KFD
- MHD Acceleration/Collimation Region: ~10 10^{2.5} № 0.5 r_S (1 - < 100 mpc; 10 № as - < 1 mas)
 The Jet "Nozzle"
- Jet Launching Region: The Accretion Flow; $\sim 5 50 r_s$
 - (0.5 5 mpc; 5 50 Mas)
 - Probably unresolved or slightly resolved

Ultra-Fast TeV Flare in Blazars

- Ultra-Fast TeV flares are observed in some Blazars.
- Vary on timescale as sort as $t_v \sim 3 \min << R_s/c \sim 3M_9$ hour
- For the TeV emission to escape pair creation $\Gamma_{em} > 50$ is required (Begelman, Fabian & Rees 2008)
- But PKS 2155-304, Mrk 501 show "moderately" superluminal ejections $(v_{app} \sim several c)$
- Emitter must be compact and extremely fast
- •Model for the Fast TeV flaring
 - Internal: Magnetic Reconnection _ inside jet (Giannios et al. 2009)
 - External: Recollimation shock (Bromberg & Levinson 2009)

PKS2155-304 (Aharonian et al. 2007) See also Mrk501, PKS1222+21



Jet Wobbling

- High resolution VLBI observations of some AGN jets show regular or irregular swings of innermost jet structural position angle (*jet wobbling*).
- Parsec scale AGN jet curvatures and helical-like structures (inner parsec or large scale) are believed to be triggered by changes in direction at the jet nozzle.
- Physical origin of jet wobbling (Agudo 2009)
 - Accretion disk precession
 - Orbital motion of accretion system (binary BH?)
 - Jet instabilities







Instability of Relativistic Jets

•When jets propagate from magnetosphere of compact object (BH, NS), there are possibility to grow of two major instabilities

- Kelvin-Helmholtz (KH) instability
 - Important at the shearing boundary flowing jet and external medium
- Current-Driven (CD) instability
 - Important in existence of twisted magnetic field
 - Twisted magnetic field is expected jet formation simulation & MHD theory
 - Kink mode (m=1) is most dangerous in such system

• Instability of relativistic jet is important for understanding observed many jet phenomena & structure

quasi-periodic wiggles, knots,
filaments, limb brightening, jet
disruption etc



Limb brightening of M87 jets (observation)

Key Questions of Jet Stability

- When jets propagate outward, there are possibility to grow of two major instabilities
 - Kelvin-Helmholtz (KH) instability
 - Important at the shearing boundary flowing jet and external medium
 - In kinetic-flux dominated jet (>10³ r_s)
 - Current-Driven (CD) instability
 - Important in existence of twisted magnetic field
 - Twisted magnetic field is expected jet formation simulation & MHD theory
 - Kink mode (m=1) is most dangerous in such system
 - In Poynting-flux dominated jet ($<10^3 r_s$)

Questions:

- How do jets remain sufficiently stable?
- What are the Effects & Structure of instabilities in particular jet configuration?

Regions of AGN Jet Propagation



CD Kink Instability

- Well-known instability in laboratory plasma (TOKAMAK), astrophysical plasma (Sun, jet, pulsar etc).
- In configurations with strong toroidal magnetic fields, current-driven (CD) kink mode (m=1) is unstable.
- This instability excites large-scale helical motions that can be strongly distort or even disrupt the system
- For static cylindrical force-free equilibria, well known Kurskal-Shafranov (KS) criterion
 - Unstable wavelengths:

 $| > | B_p / B_f | 2 p R$

- However, rotation and shear motion could significant affect the instability criterion
- Distorted magnetic field structure may trigger of magnetic reconnection. (short-time variability)



Schematic picture of CD kink instability



3D RMHD simulation of CD kink instability in PWNe (Mizuno et al. 2011)

CD Kink Instability in Jets (Newtonian) Appl et al. (2000)

• Consider force-free field with different radial pitch profile in the rest frame of jet

- maximum growth rate: $G_{max} = 0.133 v_A / P_{0}$
- unstable wave length: $I_{max} = 8.43P_0$



Maximum growth rate and unstable wave number for m=-1 kink as a function of magnetic Pitch

 $(P_0 = a \text{ in our notation:})$ Magnetic pitch $= RB_z/B_f$







Growth rate for $m=-1\sim-4$ in constant pitch case.

Previous Work for CD Kink Instability

- For relativistic force-free configuration
 - Linear mode analysis provides conditions for the instability but say little about the impact instability has on the system (Istomin & Pariev (1994, 1996), Begelman(1998), Lyubarskii(1999), Tomimatsu et al.(2001), Narayan et al. (2009))
 - Instability of potentially disruptive kink mode must be followed into the non-linear regime
- Helical structures have been found in Newtonian / relativistic simulations of magnetized jets formation and propagation (e.g., Nakamura & Meier 2004; Moll et al. 2008; McKinney & Blandford 2009; Mignone et al. 2010)

Purpose

- We investigate detail of non-linear behavior of relativistic CD kink instability
 - Relativistic: not only moving systems with relativistic speed but any with magnetic energy density comparable to or greater than the plasma energy density.
 - We start from static configurations because in the case of interest, the free energy is the magnetic energy, not kinetic energy
 - First task: static configuration (in generally, rigidly moving flows considered in the proper frame) are the simplest ones for studying the basic properties of the kink instability.

Purpose

- **Previous**: we have investigated the stability and nonlinear behavior of CD kink instability in a static plasma column (Mizuno et al. 2009)
- Here: we investigate the influence of jet rotation on the stability and nonlinear behavior of CD kink instability.
- We consider differentially rotating relativistic jets motivated from analytical work of Poynting-flux dominated jets (Lyubarsky 2009).
- In cylindrically equilibrium configurations (close to force-free), the poloidal and toroidal fields are comparable in the comoving frame.
- The jet structure relaxes to a locally equilibrium configuration if the jet is narrow enough (the Alfven crossing time is less than the proper propagation time).

4D General Relativistic MHD Equation

• General relativistic equation of conservation laws and Maxwell equations:

 $\nabla_{n}(rU^{n}) = 0 \qquad \text{(conservation law of particle-number)}$ $\nabla_{n}T^{mn} = 0 \qquad \text{(conservation law of energy-momentum)}$ $\partial_{m}F_{nl} + \partial_{n}F_{lm} + \partial_{l}F_{mn} = 0 \qquad \text{(Maxwell equations)}$ $\nabla_{m}F^{mn} = -J^{n}$

- Ideal MHD condition: $F_{nm}U^n = 0$
- metric: $ds^2 = -a^2 dt^2 + g_{ij} (dx^i + b^i dt) (dx^j + b^j dt)$
- Equation of state : p=(G-1) u

r: rest-mass density. *p* : proper gas pressure. *u*: internal energy. *c*: speed of light.

h : specific enthalpy, h = l + u + p / r.

G: specific heat ratio.

 U^{mu} : velocity four vector. J^{mu} : current density four vector.

 ∇^{mn} : covariant derivative. g_{mn} : 4-metric. *a*: lapse function, b^i : shift vector, g_{ij} : 3-metric T^{mn} : energy momentum tensor, $T^{mn} = pg^{mn} + rh U^m U^n + F^{ms}F^n_s - g_{mn}F^{lk}F_{lk}/4$. F_{mn} : field-strength tensor,

Conservative Form of GRMHD Equations (3+1 Form)

 $\frac{1}{\sqrt{-a}}\frac{\partial}{\partial t}(\sqrt{\gamma}D) + \frac{1}{\sqrt{-a}}\frac{\partial}{\partial x^{i}}(\sqrt{-g}D\tilde{v}^{i}) = 0,$ (Particle number conservation) $\frac{1}{\sqrt{-a}}\frac{\partial}{\partial t}(\sqrt{\gamma}S_i) + \frac{1}{\sqrt{-a}}\frac{\partial}{\partial x^i}(\sqrt{-g}T_i^j) = T^{\mu\nu}\left(\frac{\partial g_{\nu i}}{\partial x^{\mu}} - \Gamma^{\sigma}_{\nu\mu}g_{\sigma i}\right) \qquad \text{(Momentum conservation)}$ $\frac{1}{\sqrt{-g}}\frac{\partial}{\partial t}(\sqrt{\gamma}\tau) + \frac{1}{\sqrt{-g}}\frac{\partial}{\partial x^{i}}[\sqrt{-g}(\alpha T^{ti} - D\tilde{v}^{i})] = \alpha \left(T^{\mu t}\frac{\partial \ln \alpha}{\partial x^{\mu}} - T^{\mu \nu}\Gamma^{t}_{\nu \mu}\right) \quad \text{(Energy conservation)}$ $\frac{1}{\sqrt{-g}}\frac{\partial}{\partial t}(\sqrt{\gamma}B^i) + \frac{1}{\sqrt{-g}}\frac{\partial}{\partial x^i}[\sqrt{-g}(\tilde{v}^jB^i - \tilde{v}^iB^j)] = 0.$ (Induction equation) U (conserved variables) F^{i} (numerical flux) S (source term) $\sqrt{-g}$: determinant of 4-metric $D = \gamma \rho.$ \sqrt{g} : determinant of 3-metric $S_i = \alpha T_i^t = (\rho h + b^2) \gamma^2 v_i - \alpha b^0 b_i$ $\tau = \alpha^2 T^{tt} - D = (\rho h + b^2)\gamma^2 - (p + b^2/2) - \alpha^2 (b^t)^2 - D.$ $\tilde{v}^i = v^i - \beta / \alpha$

Detailed Features of the Numerical Schemes Mizuno et al. 2006a, 2011c and

progress

• **RAISHIN** utilizes conservative, high-resolution shock capturing schemes (Godunov-type scheme) to solve the 3D GRMHD equations *(metric is static)*

- * *Reconstruction:* PLM (Minmod & MC slope-limiter function), convex ENO, PPM, WENO5, MP5, MPWENO5
- * Riemann solver: HLL, HLLC, HLLD approximate Riemann solver
- * Constrained Transport: Flux CT, Fixed Flux-CT, Upwind Flux-CT
- * *Time evolution:* Multi-step Runge-Kutta method (2nd & 3rd-order)
- * *Recovery step:* Koide 2 variable method, Noble 2 variable method, Mignore-McKinney 1 variable method
- * *Equation of states:* constant G-law EoS, variable EoS for ideal gas

RAISHIN Code (3DGRMHD)

Mizuno et al. 2006a, 2011c, & progress

• **RAISHIN** utilizes conservative, high-resolution shock capturing schemes (Godunov-type scheme) to solve the 3D ideal GRMHD equations *(metric is static)*

Ability of RAISHIN code

- Multi-dimension (1D, 2D, 3D)
- Special & General relativity (static metric)
- Different coordinates (RMHD: Cartesian, Cylindrical, Spherical and GRMHD: Boyer-Lindquist of non-rotating or rotating BH)
- Different schemes of numerical accuracy for numerical model (spatial reconstruction, approximate Riemann solver, constrained transport schemes, time advance, & inversion)
- Using constant G-law and approximate Equation of State (Synge-type)
- Parallel computing (based on OpenMP, MPI)

Ability of RAISHIN code

- Multi-dimension (1D, 2D, 3D)
- Special and General relativity (static metric)
- Different coordinates (RMHD: Cartesian, Cylindrical, Spherical and GRMHD: Boyer-Lindquist of non-rotating or rotating BH)
- Different spatial reconstruction algorithms (7)
- Different approximate Riemann solver (4)
- Different constrained transport schemes (3) or divergence cleaning schemes (1)
- Different time advance algorithms (2)
- Different recovery schemes (3)
- Using constant G-law and variable Equation of State (Synge-type)
- Parallelized by OpenMP, MPI

Initial Condition

Mizuno et al. (2012)

- Differential rotation relativistic jet with force-free helical magnetic field
- Magnetic pitch $(P=RB_z/B_f)$: constant
- Angular velocity ($W_0=0,1,2,4,6$)
- Density profile: decrease $(r=r_0 B^2)$
- Numerical box: -3L < x, y < 3L, 0 < z < 3L (Cartesian coordinates: 240 x 240 x 120 zones)
- Boundary: periodic in axial (z) direction
- Small velocity perturbation with m=1 and $n=0.5 \sim 4$ modes

$$v_R/c = \frac{\delta v}{N} \exp\left(-\frac{R}{R_p}\right) \sum_{n=1} \cos(m\theta) \sin\left(\frac{\pi nz}{L_z}\right)$$

Force-Free Helical Magnetic Field and Velocity

Force-free equilibrium:
$$\frac{\Omega B_z}{c^2} \frac{d}{dR} \Omega R^2 B_z = B_z \frac{dB_z}{dR} + \frac{B_\phi}{R} \frac{dB_\phi}{dR}$$

Choose poloidal magnetic field: $B_z = \frac{B_0}{[1 + (R/R_0)^2]^{\alpha}}$

Choose Angular velocity:
$$\Omega = \begin{cases} \Omega_0 & \text{if } R \le R_0 \\ \Omega_0 (R_0/R)^\beta & \text{if } R > R_0 \end{cases}$$

Find toroidal magnetic field:

 B_0 : magnetic amplitude R_0 : characteristic radius $R_0 = 1/4L$ in this work *a*: pitch profile parameter **b**: differential rotation parameter a=1, b=1 in this work

$$B_{\phi} = -\frac{B_0}{R[1 + (R/R_0)^2]^{\alpha}} \sqrt{\frac{\Omega^2 R^4}{c^2}} + \frac{R_0^2 [1 + (R/R_0)^2]^{2\alpha} - R_0^2 - 2\alpha R^2}{2\alpha - 1}$$

Magnetic pitch ($P = RB_{r}/B_{f}$) :

Jet Velocity

$$P = R^{2} \sqrt{\frac{2\alpha - 1}{(2\alpha - 1)(\Omega R^{2}/c)^{2} + R_{0}^{2}[1 + (R/R_{0})^{2}]^{2\alpha} - R_{0}^{2} - 2\alpha R^{2}}$$
Jet Velocity
$$v_{z} = -\frac{B_{\phi}B_{z}}{B^{2}}\Omega R,$$
(Drift velocity):
$$v_{\phi} = (1 - \frac{B_{\phi}^{2}}{B^{2}})\Omega R.$$

Initial Radial Profile

solid: $W_0=0$ dotted: $W_0=1$ dashed: $W_0=2$ dash-dotted: $W_0=4$ dash-two-dotted: $W_0=6$



Time Evolution of 3D Structure

• Displacement of the initial force-free helical field leads to a helically twisted magnetic filament around the density isosurface with n=1 mode by CD kink instability

• From transition to non-linear stage, helical twisted structure is propagates in flow direction with continuous increase of kink amplitude.

• The propagation speed of kink ~0.1c (similar to initial maximum axial drift velocity)















• First bump at t < 20 in E_{kin} is initial relaxation of system

- Initial exponential linear growth phase from t ~ 40 to t ~ 120 (dozen of Alfven crossing time) in all cases
- Agree with general estimate of growth rate, $G_{max} \sim 0.1 v_A / R_0$
- Growth rate of kink instability does not depend on jet rotation velocity

Dependence on Jet Rotation Velocity: 3D Structure

- $W_0=2$ case: very similar to $W_0=1$ case, excited n=1 mode
- $W_0=4$ & 6 cases: n=1 & n=2 modes start to grow near the axis region
- It is because pitch decrease with increasing W_0
- In nonlinear phase, n=1 mode wavelength only excited in far from the axis where pitch is larger
- Propagation speed of kink is increase with increase of angular velocity



 $\Omega=4.0$





t=180

Ω=6.0





Ω=2.0

Multiple Mode Interaction

- In order to investigate the multiple mode interaction, perform longer simulation box cases with W₀=2 & 4
 W₀=2 case: n=1 & n=2 modes grow near the axis region (n=1 mode only in shorter box case)
- In nonlinear phase, growth of the CD kink instability produces a complicated radially expanding structure as a result of the coupling of multiple wavelengths
- Cylindrical jet structure is almost disrupted in long-term evolution.
- The coupling of multiple unstable wavelengths is crucial to determining whether the jet is eventually disrupted.

Ω=2.0









CD kink instability of Sub-Alfvenic Jets: Spatial Properties Mizuno et al. 2013, in prep

Initial Condition

• Cylindrical sub-Alfvenic (top-hat) nonrotating jet established across the computational domain with a helical force-free magnetic field

-
$$V_j = 0.2$$
c, $R_j = 1.0$

• Radial profile: Decreasing density with constant magnetic pitch (a=1/4L)

• Jet spine precessed to break the symmetry ($\sim 3L$)

Preliminary Result

• Precession perturbation from jet inlet produces the growth of CD kink instability with helical density distortion.

• Helical structure propagates along the jet with continuous growth of kink amplitude in non-linear phase. 3D density with magnetic field lines t=L/c



Summery

- In rotating relativistic jet case, developed helical kink structure propagates along jet axis with continuous growth of kink amplitude.
- The growth rate of CD kink instability does not depend on the jet rotation.
- The coupling of multiple unstable wavelengths is crucial to determining whether the jet is eventually disrupted in nonlinear stage.
- The strongly deformed magnetic field via CD kink instability may trigger of magnetic reconnection in the jet (need Resistive Relativistic MHD simulation).



Relativistic Magnetic Reconnection using RRMHD Code Mizuno 2013, ApJS

Assumption

• Consider Pestchek-type magnetic reconnection

Initial condition

- Harris-type model (anti-parallel magnetic field)
- Anomalous resistivity for triggering magnetic reconnection (r<0.8)

Results

- B-filed : typical X-type topology
- Density : Plasmoid
- Reconnection outflow: ~0.8c

Future works

- Effect of jet rotation for development of CD kink instabilities
- Coupling of CD kink/KH instabilities of super-Alfvenic jets
 - Temporal and spatial properties
- Relativistic magnetic reconnection
 - Development of resistive relativistic MHD code
- Effect of perturbation for Relativistic jet formation
 - Relation between disk perturbation and formed jet structure
- Radiation image/polarization from relativistic jet formation and propagation

Other Research

- General relativistic MHD simulations of collapsar as the central engine of GRBs (Mizuno et al. 2004ab)
- Development of 3D general relativistic MHD code RAISHIN (Mizuno et al. 2006a, 2011c)
- General relativistic MHD simulations of relativistic jet formation from thin Keplerian disk (Mizuno et al. 2006b, Hardee et al. 2007)
- Radiation imaging from BH-accretion disk system (Wu et al. 2008)
- MHD effect for relativistic shock and additional jet acceleration (Mizuno et al. 2008, 2009)
- Magnetic Field Amplification by relativistic turbulence in propagating relativistic shock (Mizuno et al. 2011a)
- Relaxation of Pulsar wind nebulae via CD kink instability (Mizuno et al. 2011b)
- Relativistic Particle-in-Cell simulations of relativistic jets (Nishikawa et al. 2009)

M87 Jet & BH



Nuclear region: $M_{bh} \sim 6 \ge 10^9 M_{sol}$, $R_s \sim 0.6$ milli-pc

Gebhardt & Thomas (2009)



Biretta, Junor & Livio (2002)





M87: BH & Jet Collimation Region

Radio Galaxy	FR Type	${ m M}_{ m BH}({ m M}_{oldsymbol{\odot}})$	D (pc)	R _S ∕ ∭as	Collimation Region Size
M87/Vir A	Ι	6.0 🕅 10 ⁹	1.67 🕅 10 ⁷	7.5	0.10 – 10 mas
Cen A	Ι	2.0 🕅 10 ⁸	3.4 ⋈ 10 ⁶	1.2	0.06 – 6 mas
Cyg A	II	2.5 😿 10 ⁹	2.2 🔀 10 ⁸	0.2	2.2 – 44 ⊠ as
Sgr A	GC	2.5 💌 10 ⁶	8,500	5.9	0.07 – 7 mas

M87 Black Hole & Jet Launching Region Largest Angular Size!



• Substructure associated with the 1st helical body mode is eliminated by sheath wind as predicted.

3D RMHD Jet Simulations & Theory

3D RMHD Jet Simulation Results at w2



Stability Properties of Spine-Sheath Relativistic Jets

Dispersion Relation: $\frac{\beta_j}{\chi_j} \frac{J'_n(\beta_j R)}{J_n(\beta_j R)} = \frac{\beta_e}{\chi_e} \frac{H_n^{(1)'}(\beta_e R)}{H_n^{(1)}(\beta_e R)}$					
J_n and $H_n^{(1)}$ are Bessel and Hankel functions and primes denote derivatives					
$\chi_j \equiv \gamma_j^2 \gamma_{Aj}^2 W_j \left(\varpi_j^2 - \kappa_j^2 v_{Aj}^2 \right) \qquad \chi_e \equiv \gamma_e^2 \gamma_{Ae}^2 W_e \left(\varpi_e^2 - \kappa_e^2 v_{Ae}^2 \right)$					
$\beta_{j}^{2} \equiv \left[\frac{\gamma_{j}^{2} \gamma_{Aj}^{2} \left(\varpi_{j}^{2} - \kappa_{j}^{2} a_{j}^{2} \right) \left(\varpi_{j}^{2} - \kappa_{j}^{2} v_{Aj}^{2} \right)}{\left(a_{j}^{2} + \gamma_{Aj}^{2} v_{Aj}^{2} \right) \varpi_{j}^{2} - \gamma_{Aj}^{2} \kappa_{j}^{2} v_{Aj}^{2} a_{j}^{2}} \right] \qquad \beta_{e}^{2} \equiv \left[\frac{\gamma_{e}^{2} \gamma_{Ae}^{2} \left(\varpi_{ex}^{2} - \kappa_{e}^{2} a_{e}^{2} \right) \left(\varpi_{e}^{2} - \kappa_{e}^{2} v_{Ae}^{2} \right)}{\left(a_{e}^{2} + \gamma_{Ae}^{2} v_{Ae}^{2} \right) \varpi_{e}^{2} - \gamma_{Ae}^{2} \kappa_{e}^{2} v_{Ae}^{2} a_{e}^{2}} \right]$					
$\varpi_{j,e}^2 \equiv (\omega - ku_{j,e})^2 \qquad \kappa_{j,e}^2 \equiv \left(k - \omega u_{j,e}/c^2\right)^2$					
$\gamma_{j,e} \equiv (1 - u_{j,e}^2/c^2)^{-1/2}$ $\gamma_{sj,e} \equiv (1 - a_{j,e}^2/c^2)^{-1/2}$ $\gamma_{Aj,e} \equiv (1 - v_{Aj,e}^2/c^2)^{-1/2}$					
$a = sound speed$ $v_A = Alfven wave speed$					
Resonance (M*) : $\frac{u_j - u_e}{1 - u_j u_e/c^2} > \frac{v_{wj} + v_{we}}{1 + v_{wj} v_{we}/c^2}$					
$v_{wj} \equiv (a_j, v_{Aj})$ and $v_{we} \equiv (a_e, v_{Ae})$ in (fluid, magnetic) limits					

 $v_w \approx v_w^* \equiv \frac{\gamma_j(\gamma_{we}v_{we})u_j + \gamma_e(\gamma_{wj}v_{wj})u_e}{\gamma_j(\gamma_{we}v_{we}) + \gamma_e(\gamma_{wj}v_{wj})}$

 $\gamma_{wj,e} \equiv (1 - v_{wj,e}^2/c^2)^{-1/2}$ for $v_{wj} \equiv (a_j, v_{Aj})$ and $v_{we} \equiv (a_e, v_{Ae})$ in (fluid, magnetic) limits

$$\omega R/v_{we} \approx \omega_{nm}^* R/v_{we} \equiv \frac{(2n+1)\pi/4 + m\pi}{\left[\left(1 - u_e/v_w^*\right)^2 - \left(v_{we}/v_w^* - u_e v_{we}/c^2\right)\right]^{1/2}}$$
$$\lambda_{nm}^* \equiv \frac{2\pi}{(2n+1)\pi/4 + m\pi} \left(\frac{\gamma_e}{v_{we}}\right) \left[\left(v_w^* - u_e\right)^2 - \left(v_{we} - \left(v_{we}u_e/c^2\right)v_w^*\right)^2\right]^{1/2} R$$

Hardee 2007 Surface Modes @ $\mathbb{K} << \mathbb{K}^{*}$ $\frac{\omega}{k} = \frac{[\eta u_{j} + u_{e}] \pm i\eta^{1/2} [(u_{j} - u_{e})^{2} - V_{As}^{2}/\gamma_{j}^{2}\gamma_{e}^{2}]^{1/2}}{(1 + V_{Ae}^{2}/\gamma_{e}^{2}c^{2}) + \eta(1 + V_{Aj}^{2}/\gamma_{j}^{2}c^{2})}$ $\eta \equiv \gamma_{j}^{2}W_{j}/\gamma_{e}^{2}W_{e}$ $V_{As}^{2} \equiv (\gamma_{Aj}^{2}W_{j} + \gamma_{Ae}^{2}W_{e}) \frac{B_{j}^{2} + B_{e}^{2}}{4\pi W_{j}W_{e}}$ $W_{j,e} \equiv \rho_{j,e} + [\Gamma/(\Gamma - 1)]P_{j,e}/c^{2}$

Body Mode Condition:

$$\left[\frac{a_j^2 u_j^2 + \gamma_{Aj}^2 v_{Aj}^2 (u_j^2 - a_j^2)}{\gamma_j^2 \gamma_{Aj}^2 (u_j^2 - a_j^2) (u_j^2 - v_{Aj}^2)}\right] > 0$$

Growth Rate Reduction: Stability:

$$\gamma_j^2 \gamma_e^2 \left(u_j - u_e \right)^2 \longrightarrow \gamma_{Aj}^2 \gamma_{Ae}^2 \left(W_j / \gamma_{Ae}^2 + W_e / \gamma_{Aj}^2 \right) \frac{B_j^2 + B_e^2}{4\pi W_j W_e}$$
$$\gamma_j^2 \gamma_e^2 \left(u_j - u_e \right)^2 < \gamma_{Aj}^2 \gamma_{Ae}^2 \left(W_j / \gamma_{Ae}^2 + W_e / \gamma_{Aj}^2 \right) \frac{B_j^2 + B_e^2}{4\pi W_j W_e}$$

Resolution Test for CD kink Simulations



- Higher resolution has faster growth rate and maximum amplitude
- Resolution of current simulation (N/L=40) is acceptable.

Dependence on Adiabatic Index for CD Kink Instability



There are no difference between different adiabatic index

Non-relativistic CD Kink Instability

Appl et al. (2000) • Consider force-free field with different radial pitch profile in the rest frame of jet

• maximum growth rate: $G_{max} = 0.133 v_A / P_0$

 $(P_0 = a \text{ in our notation})$

2

kR

3

0.4



Г_{тех} R/v_A, k_{тех} R 0.001 0.001 0.3 0.0001 N 10.2 10-5 10-6 0.01 0.1 1 10 100 1000 (P_n/R)⁻¹ 0.1 Maximum growth rate and unstable wave number for m=-1 kink as a 0 function of characteristic radius of column

1000

100

10

m =